Course Form for PKU Summer School International 2025

Course Title	Title in English: Introduction to Affective Intelligent Robotics
	Title in Chinese: 情感智能机器人引论
Teacher	王韬 Tao WANG
First day of classes	June 30, 2025
Last day of classes	July 25, 2025
Course Credit	2 credits

Course Description

Objective:

- 1. Let students understand the historical development and key technologies of affective intelligent robots;
- 2. Enable students to master the core concepts of hardware and software of affective intelligent robot system;
- 3. Let students have an understanding on the important research fields of affective intelligent robots, enable them to conduct more in-depth research in the future.

Pre-requisites /Target audience

Undergraduate and graduate students with unlimited majors

Proceeding of the Course

The course is a four-week, 32 hours program scheduled for June 30 to July 25 2025, sessions will combine class teaching and discussion.

Assignments (essay or other forms)

One Essay submitted by the end of the course

Evaluation Details

- Participation: 50%
- Essay: 50%

Text Books and Reading Materials

Handbook of Robotics 2nd Ed. Bruno Siciliano, Oussama Khatib (Eds.) Springer 2016 978-3-319-32550-7

Academic Integrity (If necessary)

CLASS SCHEDULE	
(Subject to adjustment)	
Session 1: The historical development of robots	Date: July 1, 2025
 (Description of the Session) (purpose, requirements, class cheduling, etc.) What is a robot? The historical development of robots. 	s and presentations
Questions Vhy "robots" instead of "machines"?	
Readings, Websites or Video Clips None	
Assignments for this session (if any) None	
Session 2: Modern robots	Date: July 2, 2025
 (Description of the Session) (purpose, requirements, class cheduling, etc.) Kinds of robots The characteristics of various kinds of robots 	s and presentations
(Questions) magine a practical scenario, what would a robot look like? Wi ave?	hat useful abilities does it
Readings, Websites or Video Clips None	
Assignments for this session (if any) None	
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- Preliminary kinematics and dynamics **[**Questions] 1. What components should a robot have? 2. Why can robots complete tasks such as movement and operation? **Readings**, Websites or Video Clips None **[**Assignments for this session (if any)**]** None Session 4: Overview of robot sensing Date: July 8, 2025 [Description of the Session] (purpose, requirements, class and presentations scheduling, etc.) General perception process ۲ Sensors commonly used for robots • [Questions] 1. What steps does a robot need to perceive the environment? 2. What sensors do robots need? **K**Readings, Websites or Video Clips None **[**Assignments for this session (if any)**]** None Session 5: Common sensing methods (part 1) Date: July 9, 2025 **[**Description of the Session **]** (purpose, requirements, class and presentations scheduling, etc.) \bullet Visual sensing Distance sensing • Inertial sensing **(**Ouestions **)** 1. What are the principles of these sensing methods?
 - 2. How to implement these sensing methods?

[Readings, Websites or Video Clips] None	
【Assignments for this session (if any)】 None	
Session 6: Common sensing methods (part 2)	Date: July 11, 2025
 [Description of the Session] (purpose, requirements, class and puscheduling, etc.) Auditory sensing Force/tactile sensing 	resentations
【Questions】1. What are the principles of these sensing methods?2. How to implement these sensing methods?	
[Readings, Websites or Video Clips] None	
【Assignments for this session (if any)】 None	
Session 7: Software architecture of intelligent robots	Date: July 15, 2025
 (Description of the Session) (purpose, requirements, class and puscheduling, etc.) Layered robot control architecture Robot Operating System (ROS) 	resentations
 (Questions) 1. What are the advantages of layered robot control structure? 2. What benefits does ROS bring to robot design/manufacturing? 	
[Readings, Websites or Video Clips] None	
【Assignments for this session (if any)】 None	
Session 8: Mobile robots	Date: July 16, 2025

[Description of the Session] (purpose, requirements, class and presentations				
scheduling, etc.)				
• Fundamentals of mobile robots				
• Simultaneous Localization and Mapping (SLAM)				
[Questions]				
1. What is the relationship between mobility planning and obstacle av	oidance? What's the			
difference?				
2. What are the commonly used map representations? Which scenario	s are they suitable			
for?				
[Readings, Websites or Video Clips]				
None				
CAssignments for this session (if any) None				
Session 9: Intelligent manipulation	Date: July 18, 2025			
[Description of the Session] (purpose, requirements, class and pu	resentations			
scheduling. etc.)				
 Grasping and manipulation tasks 				
 Singularity 				
 Compliant motion 				
Visual servoing				
[Ouestions]				
What constraints should be considered during manipulation planning				
1. What constraints should be considered during manipulation planning	1g: 			
2. when is compliant motion required? when is visual servoing requi	red?			
[Readings, Websites or Video Clips]				
None				
[Assignments for this session (if any)]				
None				
INOILE				
Session 10: Affective intelligent robots	Date: July 22, 2025			
【Description of the Session】 (purpose, requirements, class and pr	resentations			
scheduling, etc.)				
• Overview of affective intelligent robots				
• Being with affective intelligent robots				
[Ouestions]				
Vucsuolis When do reports need offection?				
when do robots need affection?				

Keadings, Websites or Video Clips None	
【Assignments for this session (if any)】 None	
Session 11: Methods for emotion recognition	Date: July 23, 2025
 (Description of the Session) (purpose, requirements, class and puscheduling, etc.) Basics of emotion recognition Multimodal emotion recognition (Questions) How can robots quickly recognize human emotions? 	esentations
<pre>【Readings, Websites or Video Clips】 None 【Assignments for this session (if any)】 None</pre>	
Session 12: <i>Roboethics</i>	Date: July 25, 2025
 Description of the Session J (purpose, requirements, class and puscheduling, etc.) Roboethics Coexistence of humans and affective intelligent robots [Questions] Are there any ethical issues for robots that you have seen? Why? 	esentations
Keadings, Websites or Video Clips None Kassignments for this session (if any)	
None	